

# The World's First Triple Nested HF Radar Test Bed for Current Mapping and Ship Detection

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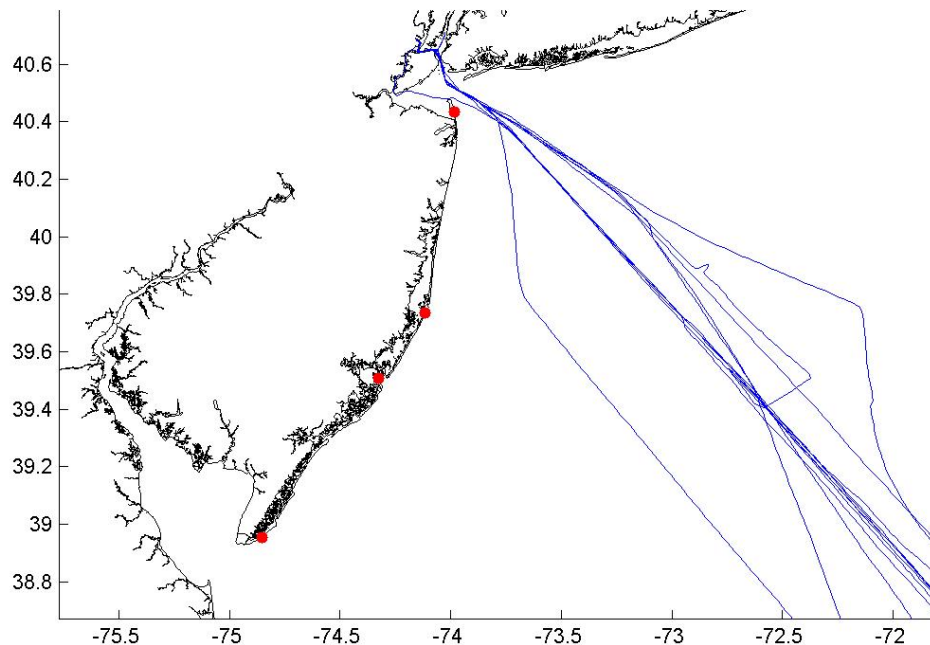
**CODAR Ocean Sensors**



# FUTURE WORK (ROW4)

## System Performance in Varied Environments

- Based upon the shown work, optimal settings have been set at all long-range sites for multi-static dual use operations
- Now focusing on a long term data set , M/V Oleander sails New York to Bermuda on a weekly basis providing ship tracking opportunities while the network continues to provide surface current maps to the Coast Guard for Search & Rescue Demonstrations.



## Multiple Frequencies

- Sandy Hook: 5, 13 and 25 MHz

## Multiple Sites

- Sandy Hook
- Lovelladies
- Tuckerton &
- Wildwood

# Ship Tracking Throughout Rutgers HF Radar Network

<i>Detection Time Period</i>	<i>Ship</i>	<i>Ship Length/Height</i>	<i>Tracked from</i>	<i>Frequency</i>	<i>Raw Data Archival &amp; Distribution</i>	<i>Detection Files Generated</i>	<i>Kalman Filter Solution Generated</i>
June 18-24, 2001	Endeavor ①	185'/84'	Sandy Hook	5 MHz	✓	✓	✓
June 19-23, 2001	Oleander ②	387'/98'	Sandy Hook	5 MHz	✓	✓	✓
November 22-24, 2002	Oleander ②	387'/98'	Sandy Hook & Loveladies	5 MHz	✓	✓	✓
December 16-19, 2002	Coast Guard Funback ③	82'/48'	Wildwood	5 MHz	✓	✓	✓
March 26, 2003	Sea Tow Greg ④	25'/13'	Tuckerton	5 MHz	✓		
April 21, 2003	Sea Tow Greg ④	25'/13'	Tuckerton	5 MHz	✓		
May 7, 2003	Rosemary Miller ⑤	95'/32'	Sandy Hook & Loveladies	5 MHz	✓		
May 20, 2003	Sea Tow Mike ⑥	20'/13'	Tuckerton	5 MHz	✓	✓	✓
July 30, 2003	Sea Tow Joe ⑦	41'/20'	Tuckerton & Loveladies	5 MHz	✓		
September 3-4, 2003	RV Connecticut ⑧	70'/50'	Sandy Hook & Loveladies	5 MHz	✓		
September 26-29, 2003	Royal Caribbean Serenade of the Seas ⑨	962'/13 decks	Sandy Hook	5 MHz	✓		
October 7, 2003	Sea Tow Greg ④	25'/13'	Loveladies	5 MHz	✓		
October 7, 2003	Sea Tow Greg ④	25'/13'	Brant Beach	25 MHz	✓		
October 8, 2003	Sea Tow Greg ④	25'/13'	Loveladies	5 MHz	✓		
October 8, 2003	Sea Tow Greg ④	25'/13'	Brant Beach	25 MHz	✓		

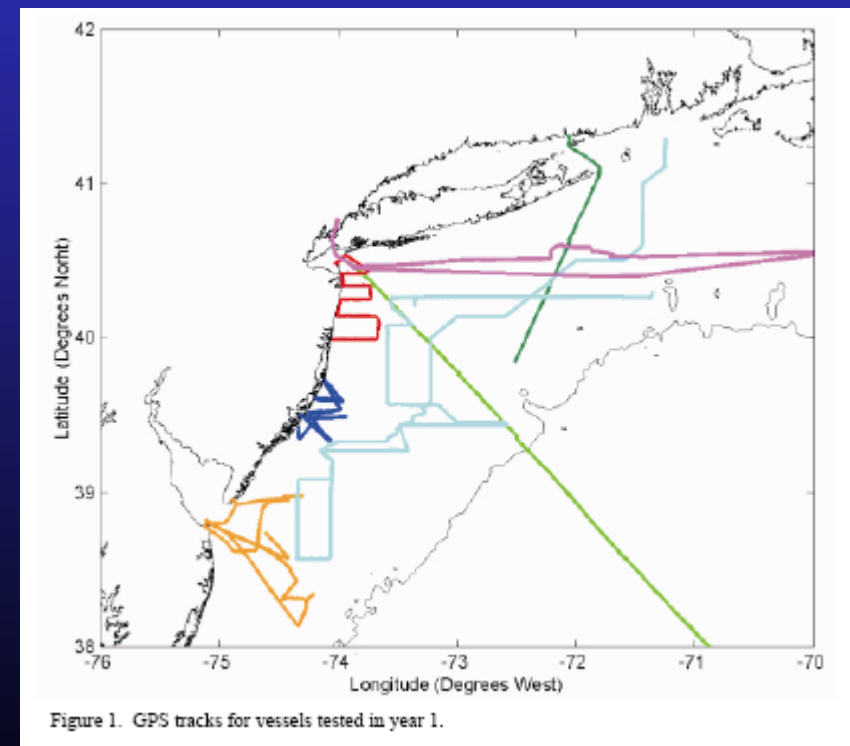
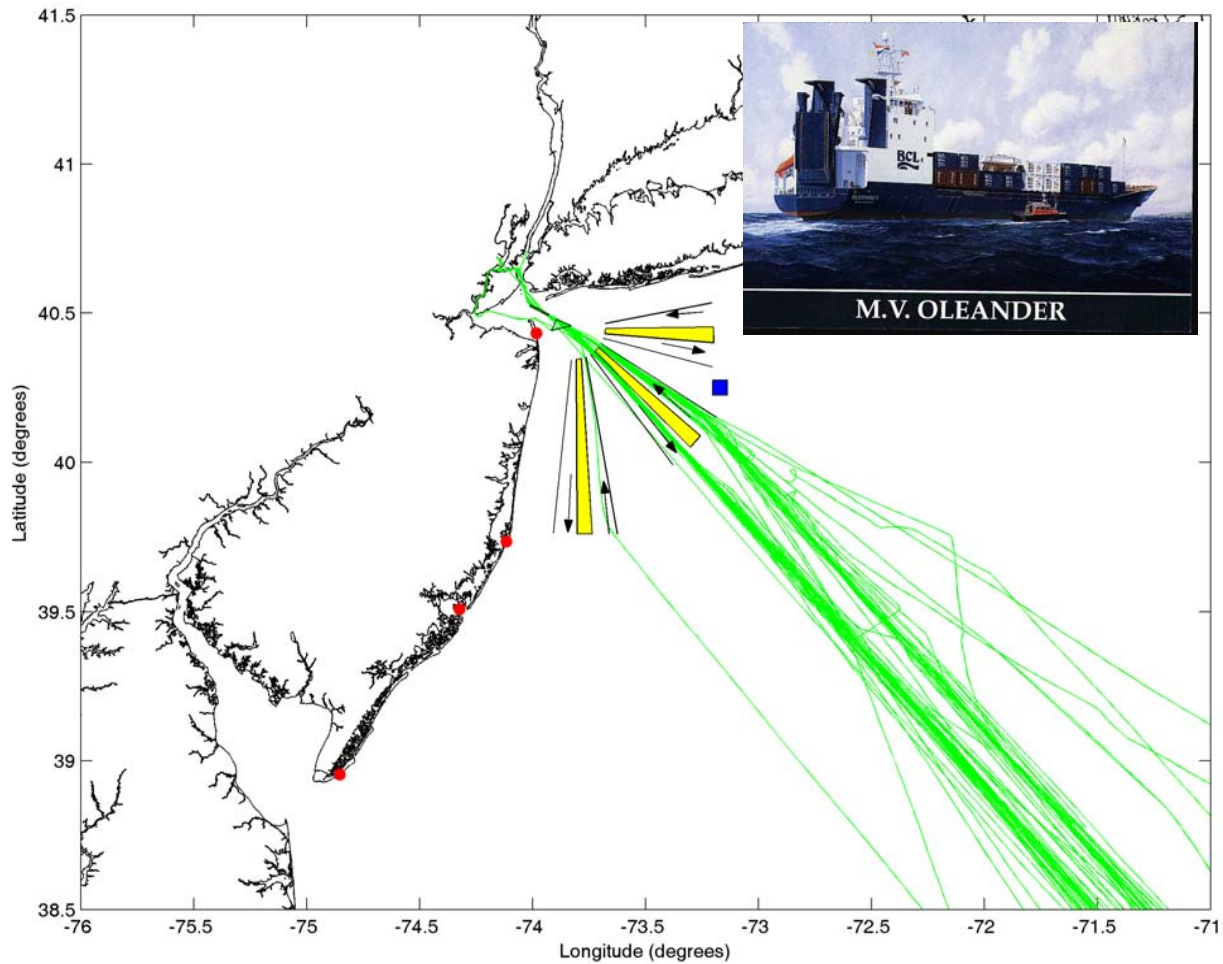


Figure 1. GPS tracks for vessels tested in year 1.

# 60 Transits of Oleander in 2005



**New Jersey  
Installations  
Used for  
Oleander  
Tests**

*5 MHz  
Lovelandies, NJ*

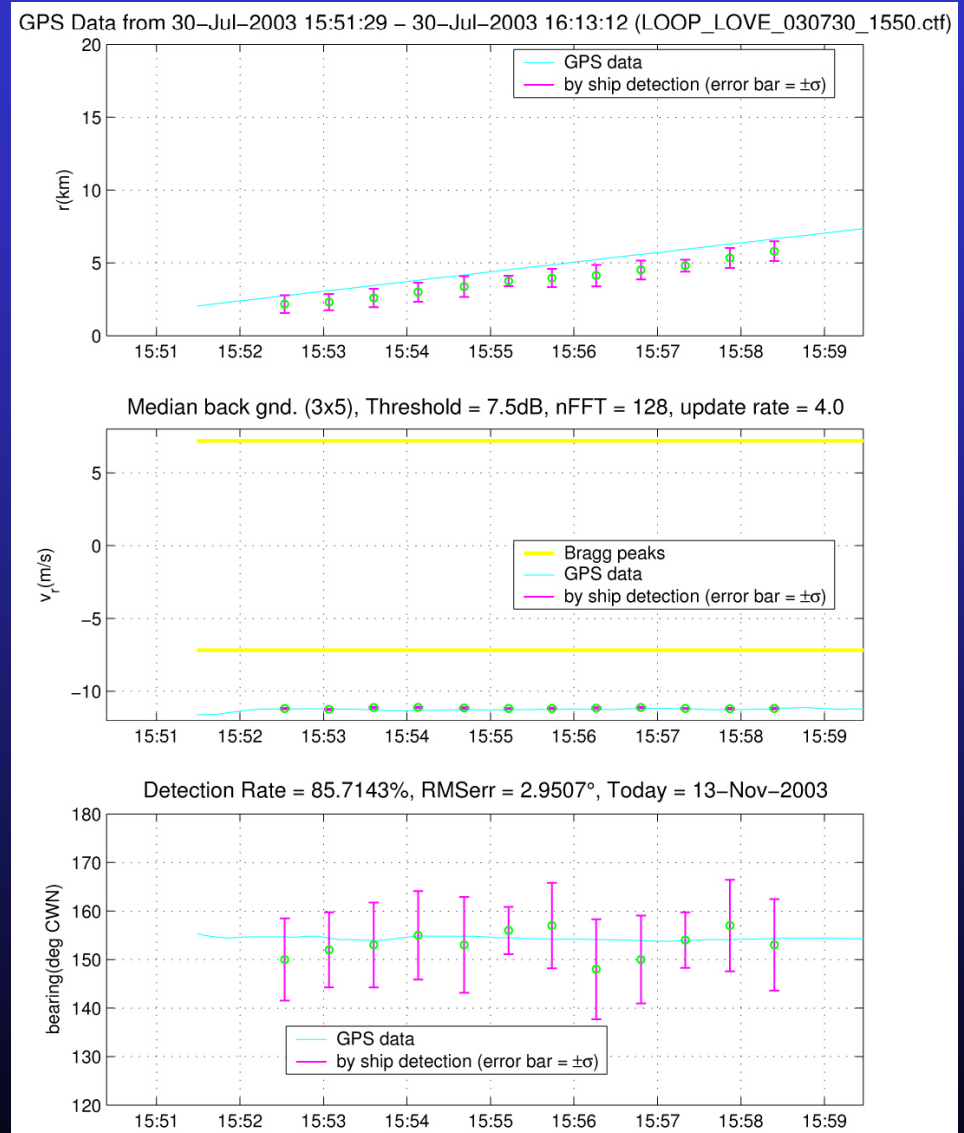


*5 MHz  
Sandy Hook ,NJ*



# Detection Algorithm

- Simultaneous multiple sliding window FFTs in Doppler processing
- Two types of background calculation --- median and IIR
- 3D background (Time, Range and Doppler) varying with sea echoes
- Thresholding of peaks --- local SNR of monopole or at least one of the two dipole antennas have to be above the threshold
- MUSIC algorithm used to determine bearing
- Bearing precision determined by SNR ( $\sim 1/\sqrt{\text{SNR}}$ )



# Oleander Detections

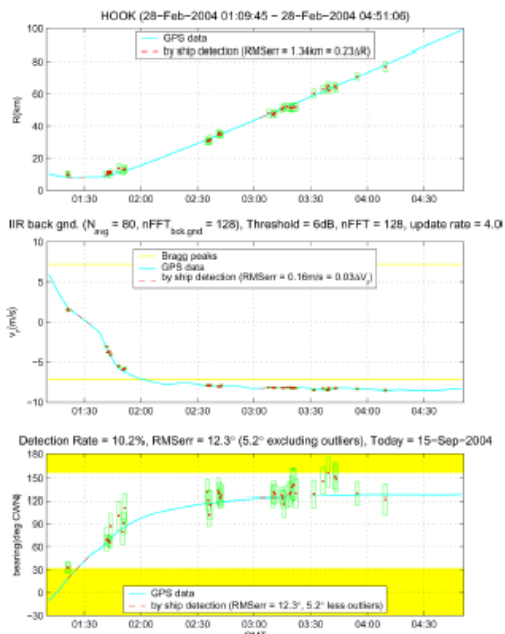


Figure 3. Oleander detection study for 128-point FFT with 6 dB detection threshold.

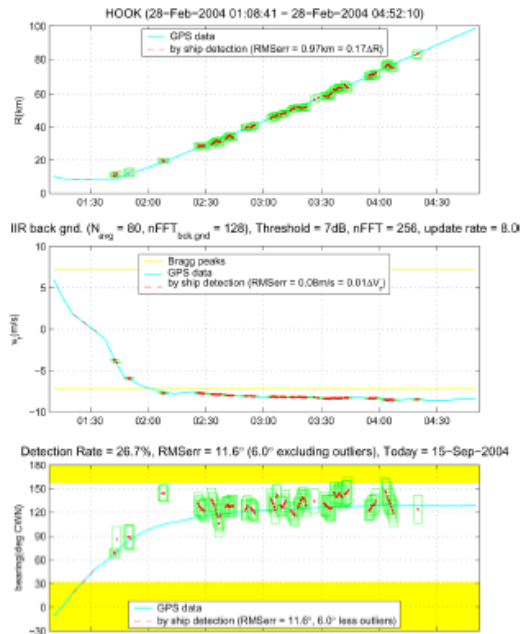


Figure 4. Oleander detection study for 256-point FFT with 7 dB detection threshold.

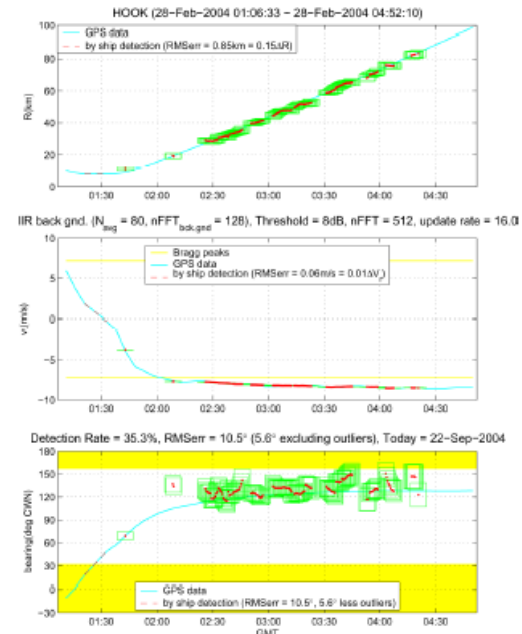


Figure 5. Oleander detection study for 512-point FFT with 8 dB detection threshold.

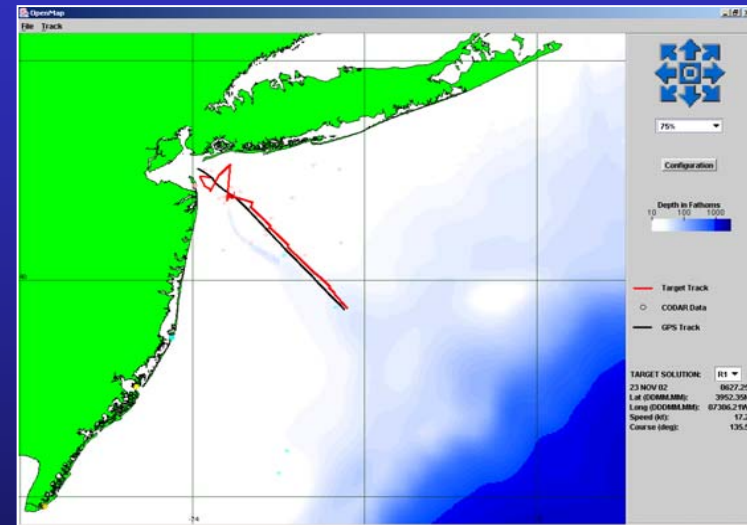
128 point FFT  
6 dB Threshold

256 point FFT  
7 dB Threshold

512 point FFT  
8 dB Threshold

# Ship Tracking Algorithm

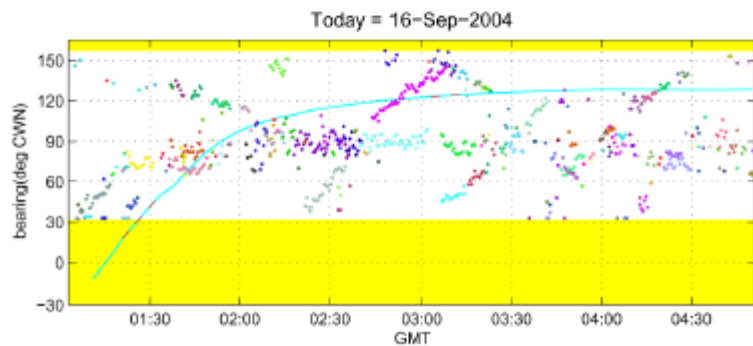
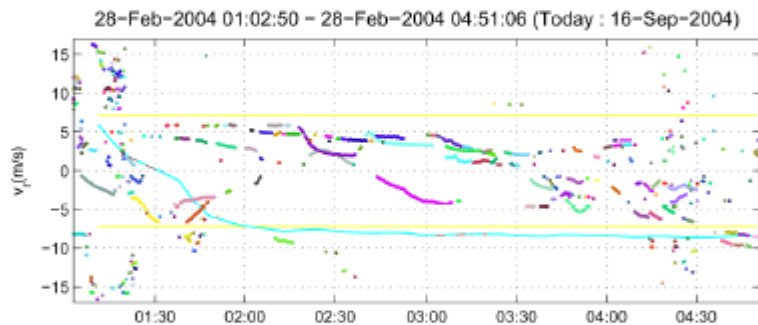
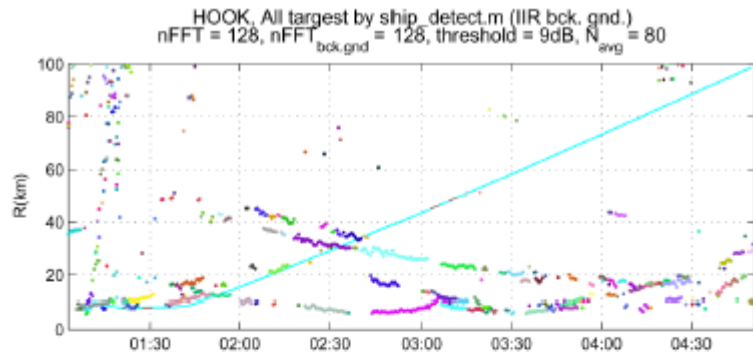
- A Kalman Filter provides a recursive solution to the least squares problem.
- Assumptions include linear target motion and normally distributed measurement errors.
- Tracker inputs are time; radar transmitter and receiver positions; range, bearing, and range rate; and range, bearing, and range rate uncertainties.
- Tracker outputs are target position; velocity; and estimates of position and velocity uncertainties (covariance matrix).
- Target Maneuver Test: a statistical test is used to estimate whether a combination of two straight tracks fit the data better than a single straight track.



*Oleander Constant Course and Speed  
Tracker Solution Using CODAR  
Detections from 23 November 2002*

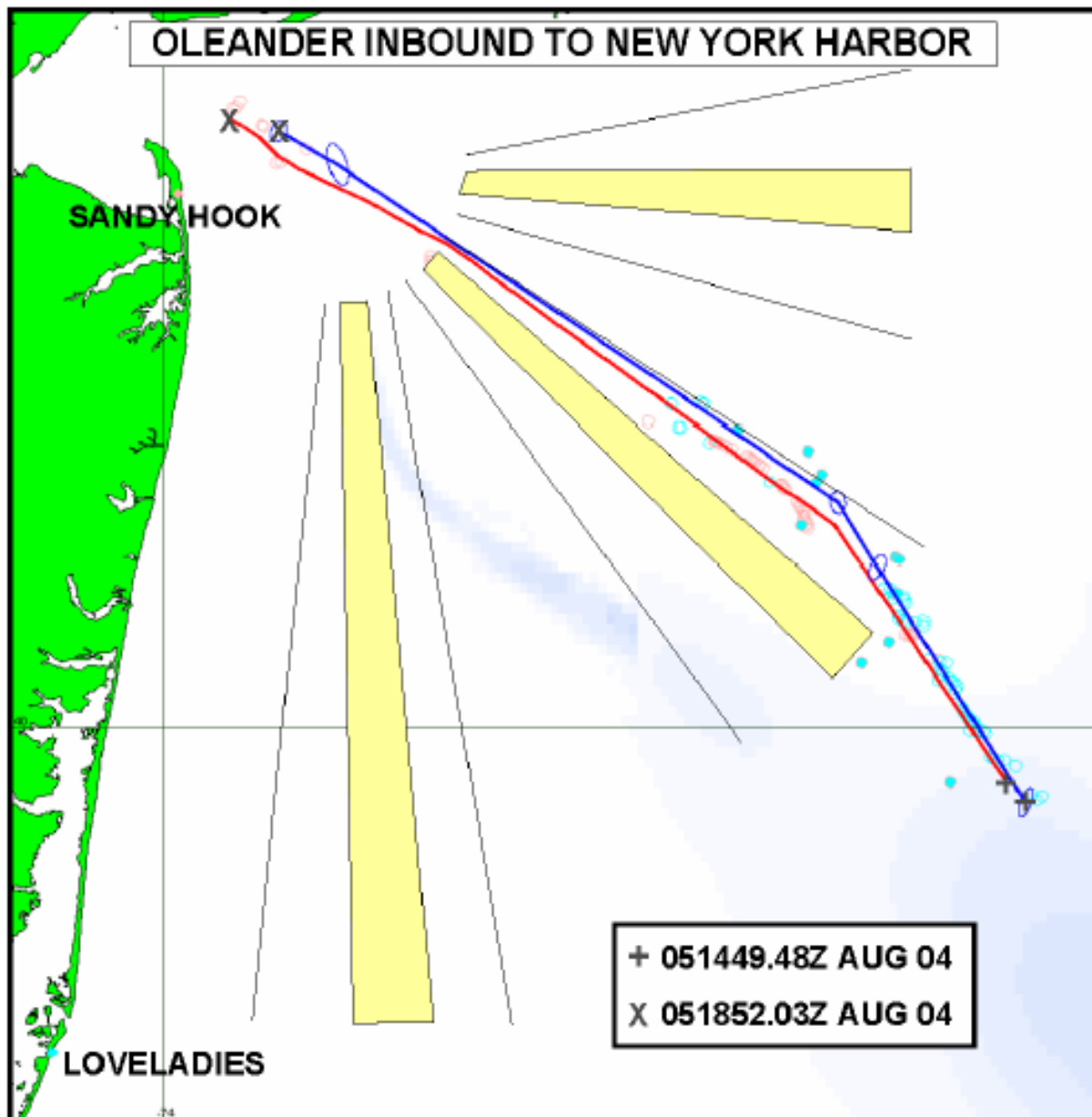


# Pepper Plots



- All targets detected 9 dB above background

# OLEANDER INBOUND TO NEW YORK HARBOR



## LEGEND

### DATA

-  LOVELADIES BACKSCATTER
-  SANDY HOOK BACKSCATTER
-  LOVELADIES/SANDY HOOK BISTATIC



### TRACKS

-  OLEANDER GPS
-  CODAR SHIP TRACKER

### SYMBOLS

-  SHIPPING LANES

### SCALE

-  10 (km)
-  10 (nm)

# Present Focus

- **Hardware Improvements**
  - 13 MHz Codar SeaSonde, December 2004
  - 13 MHz Codar Superdirective System, July 2005
- **Software Improvements**
  - SIFTER Algorithm

# Sandy Hook Facility March 2004

Continuous  
Operation Since  
July 2001



# Sandy Hook

## Test Bed

### Present Day

- 25 MHz system installed March 2004
- 5 MHz Transmit Antenna moved 1 wavelength back from shoreline
- 13 MHz System Installed December 2004



5 MHz Rx



25 MHz  
Tx/Rx



13 MHz Tx



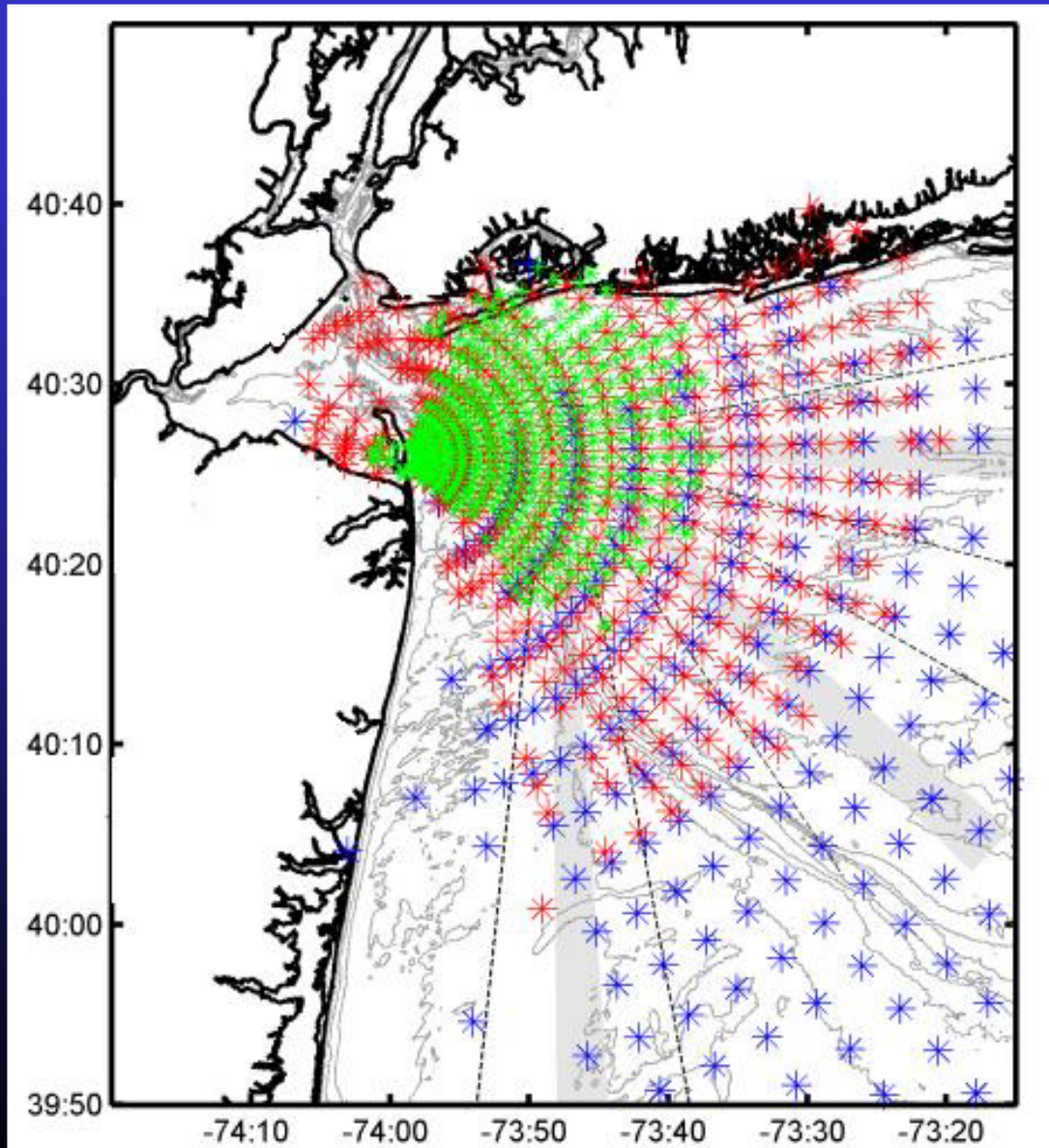
13 MHz Rx



5 MHz Tx



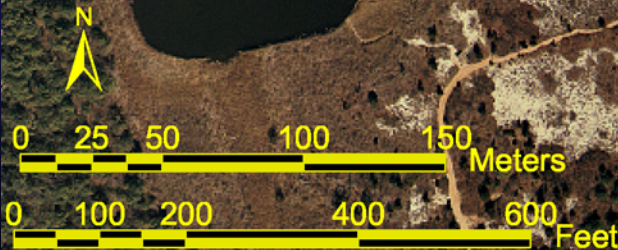
# Three Frequency Coverage



- 5 MHz
- 13 MHz
- 25 MHz

How did the  
move of the  
Transmit  
Antenna Affect  
Radial  
Coverage?

● 5 MHz Rx  
● 5 MHz Tx  
● 5 MHz Tx



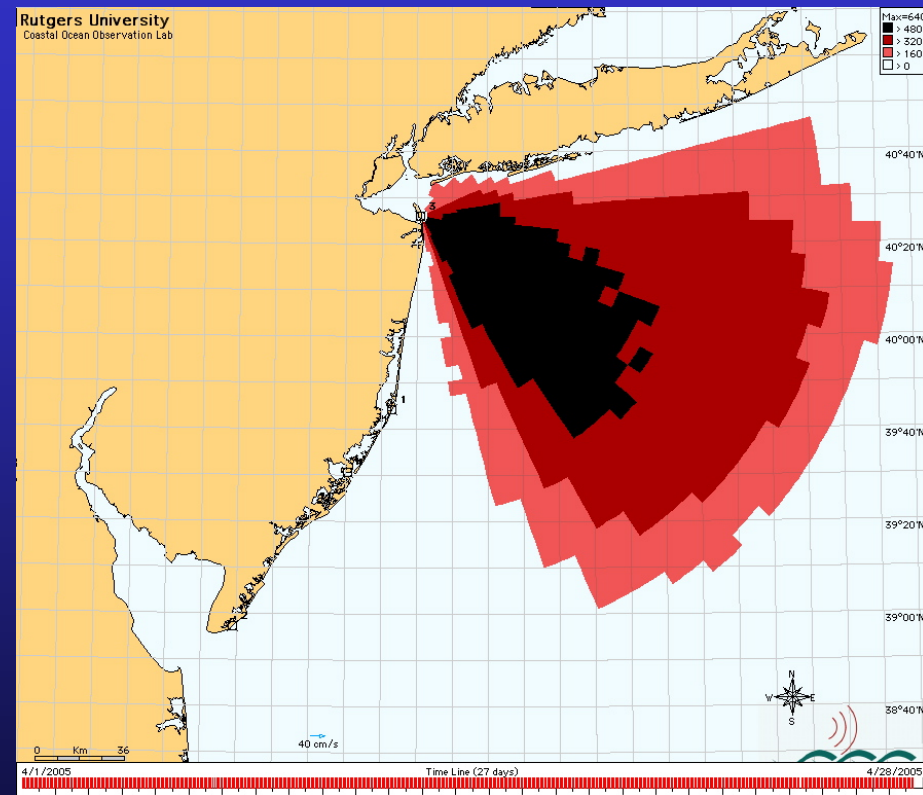
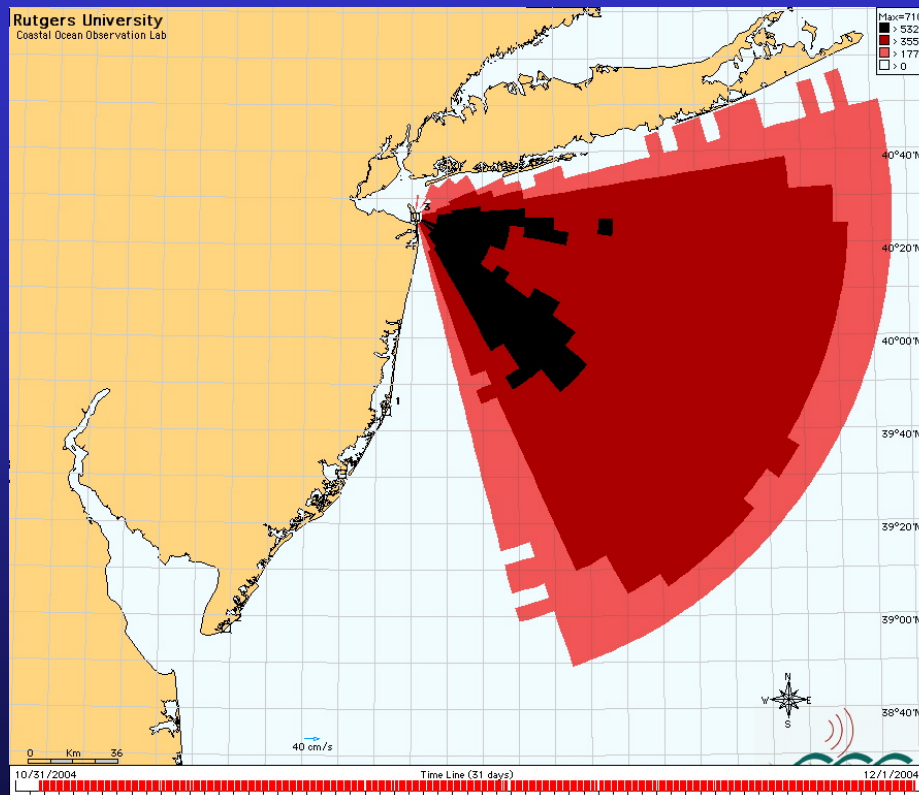
1995 Aerial Photography



# 5 MHz Transmit Antenna Move

## BEFORE

## AFTER



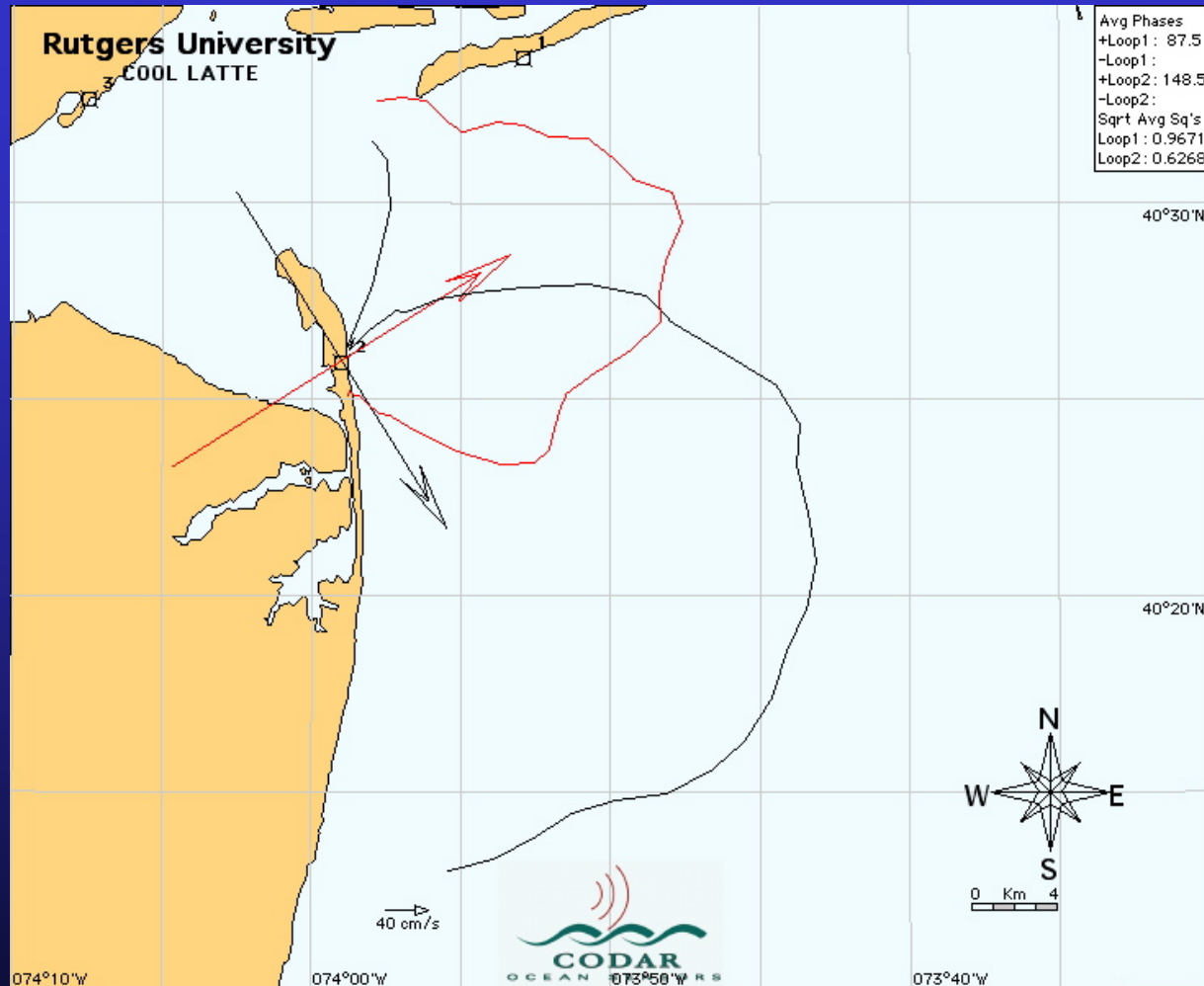
Radial Distribution  
November 2004

Radial Distribution  
April 2005

# 5 & 13 MHz Receive Antennas in “Cluttered” Environment

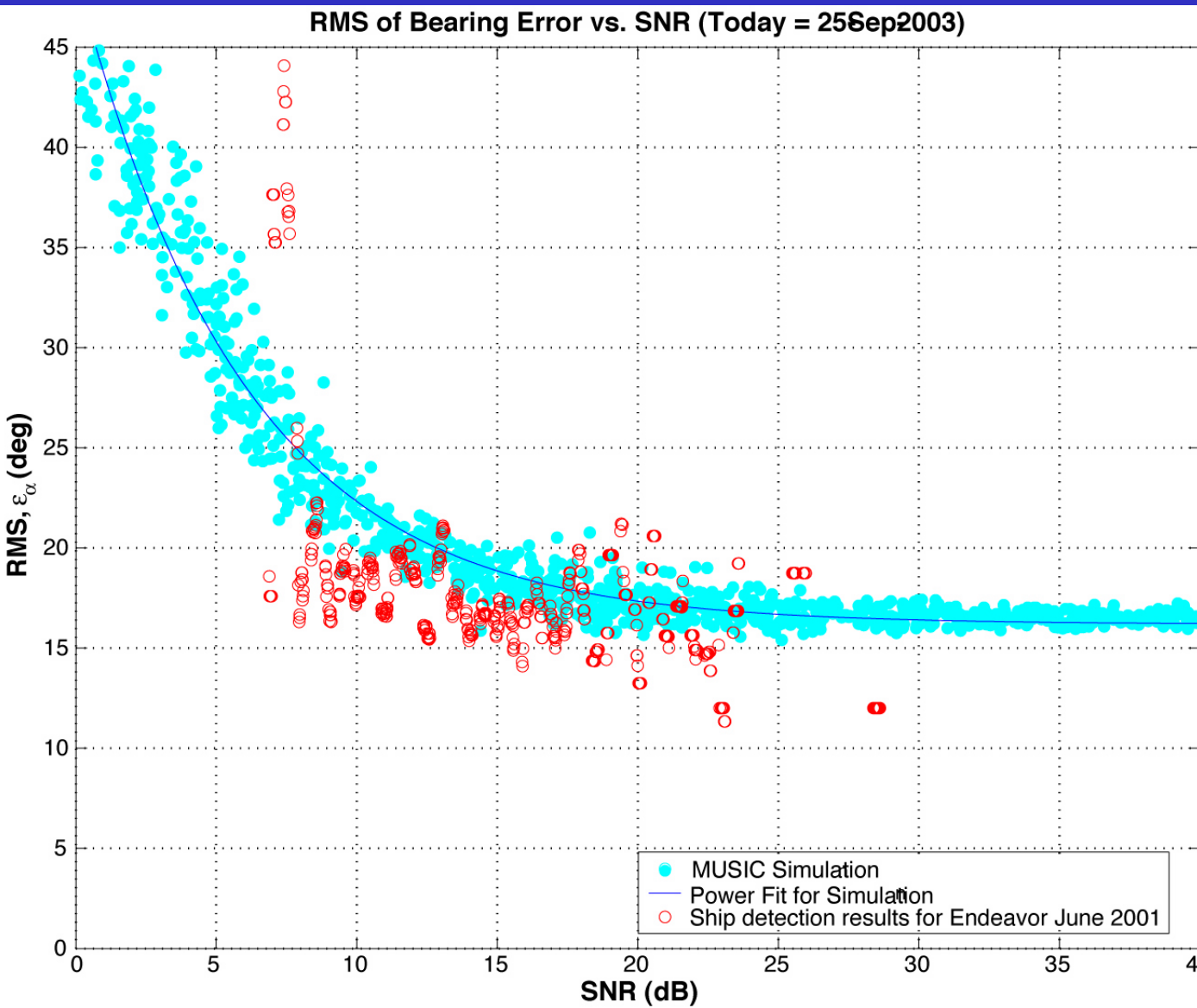


# 5 MHz HOOK



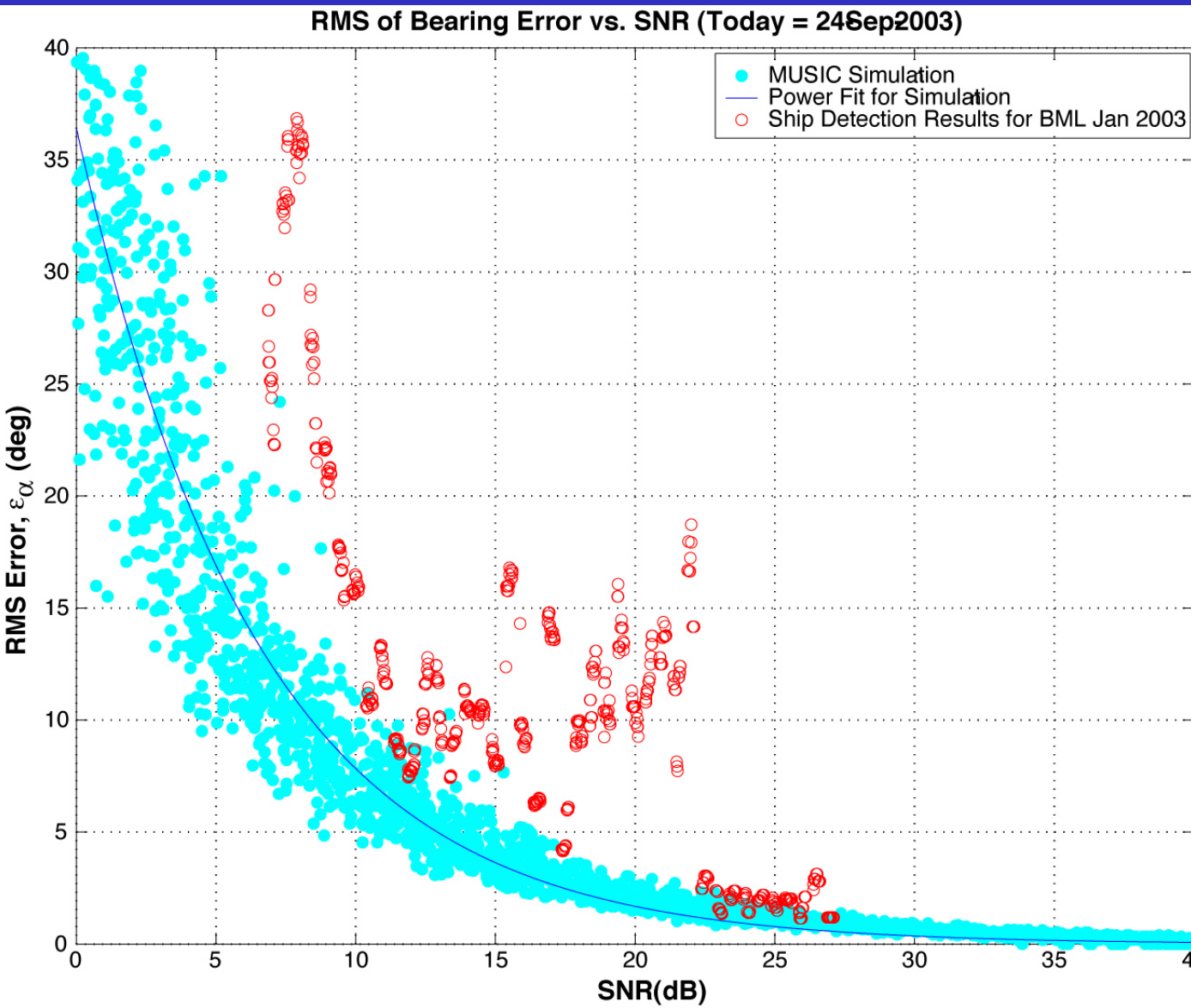
## Pattern Measurement

# Simulated Bearing Error with Added Bias from Improper Antenna Pattern Compared with Real Ship Bearing Data



- For Simulation:
  - Measured distorted pattern inputted
  - Ideal pattern used to recover echo
- Expected power-law fit is offset by  $16^\circ$
- Ship is also offset when inappropriate ideal pattern is used

# Simulated Bearing Error with Distorted, Measured Antenna Patterns Compared with Real Ship Bearing Data



- Simulated points follow power law:

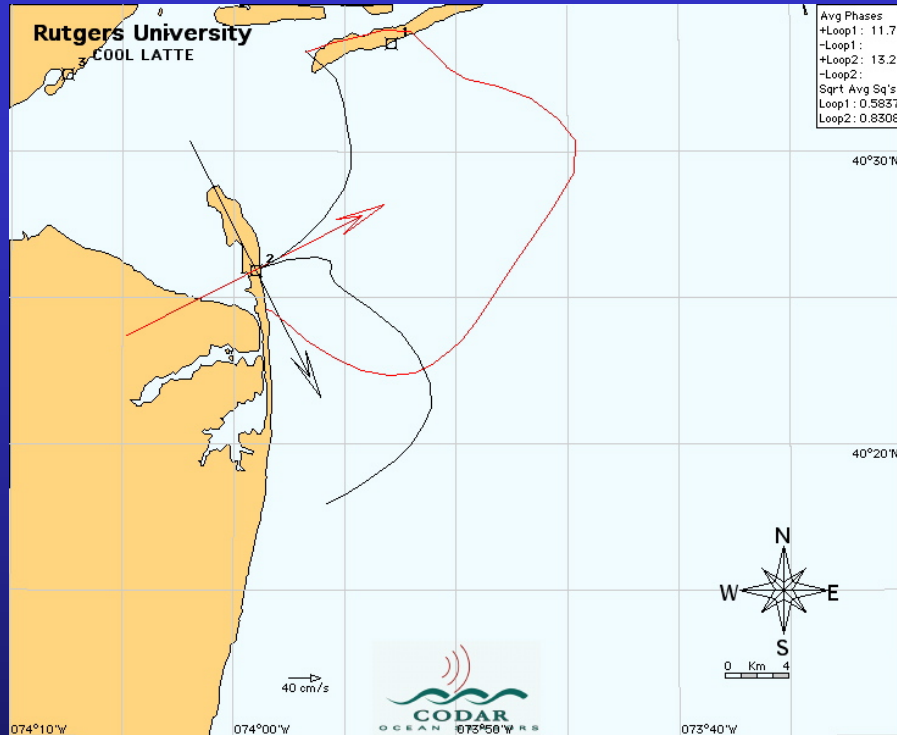
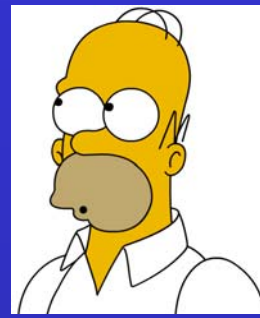
$$\sigma_B = \frac{36.4}{\text{SNR}^{0.67}}$$

- Compared to:

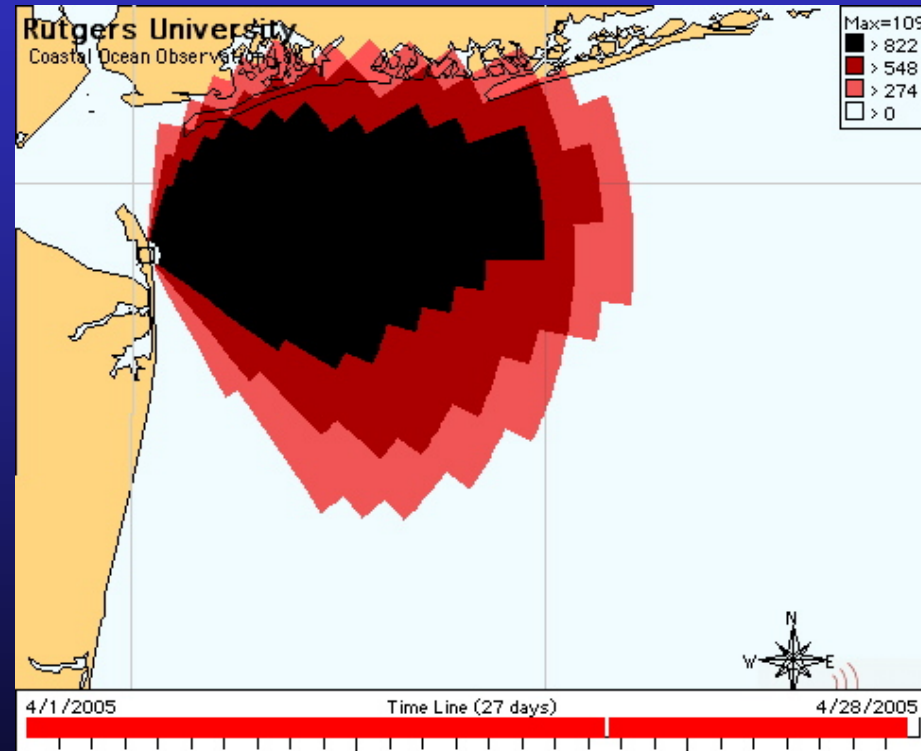
$$\sigma_B = \frac{40}{\text{SNR}^{0.5}}$$

- Ship detections at lower SNRs may differ because:
  - Noise peaks are mis-identified as ships
  - "Noise" near peak contains ship signal, i.e., it is too high

# 13 MHz HOMR



## Pattern Measurement

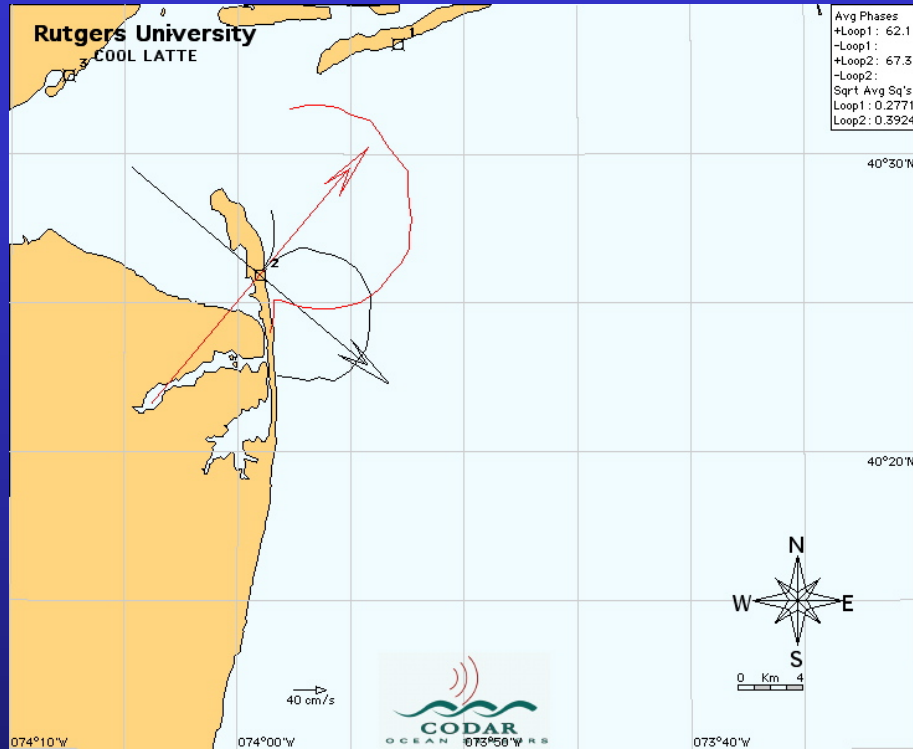


## Radial Distribution

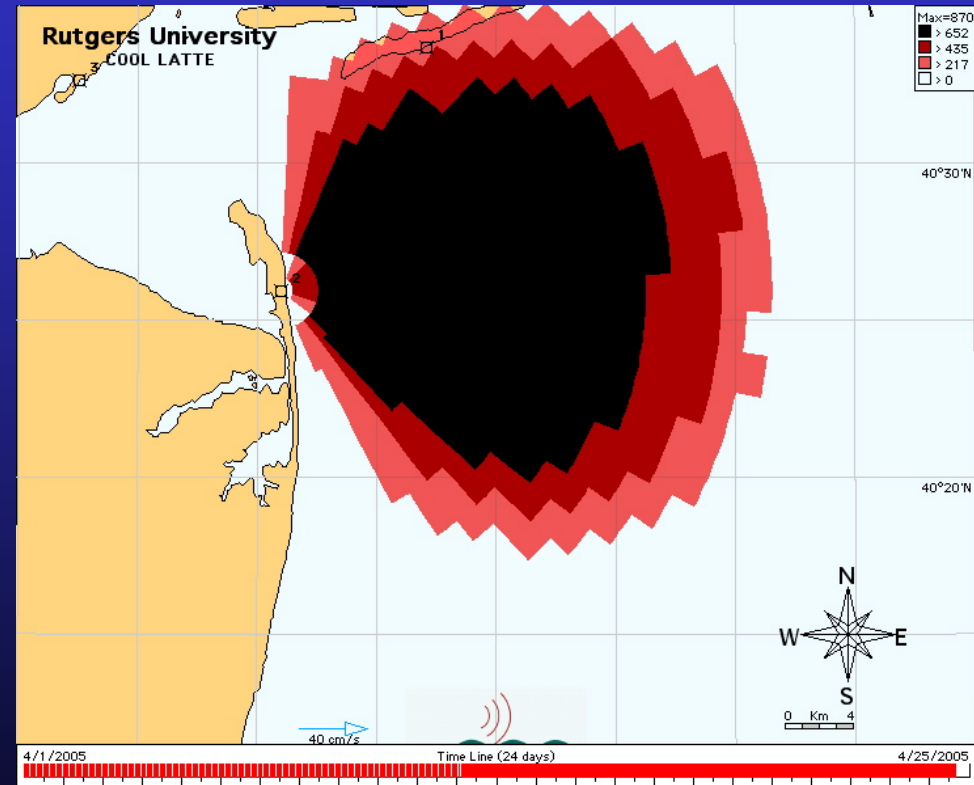
# 25 MHz System in Clear Environment



# 25 MHz HOSR



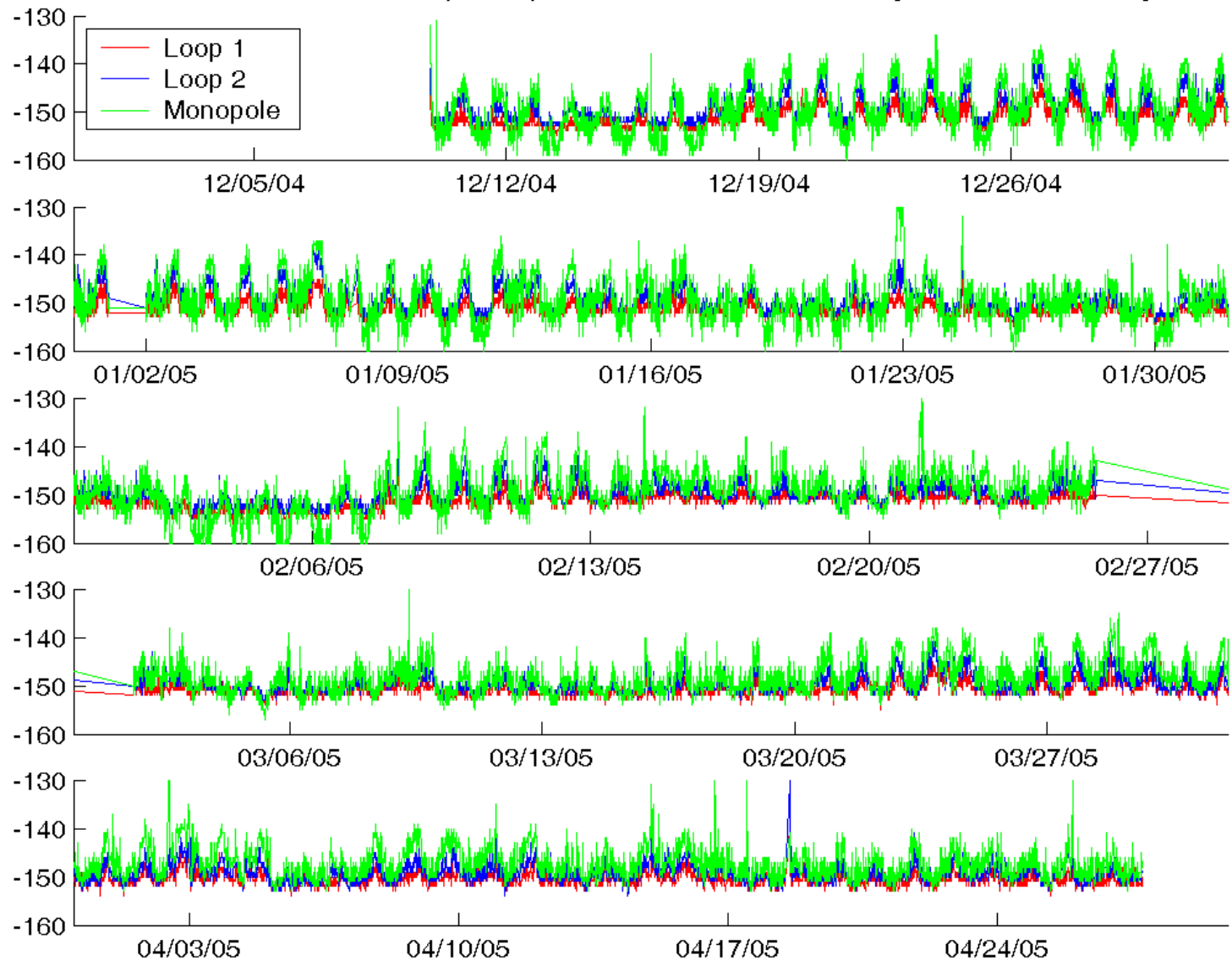
## Pattern Measurement



## Radial Distribution



# Noise Floor Measurements (dBm) for 13 MHz Codar System at Sandy Hook, NJ



# Sandy Hook

## Test Bed

### Future

- 13 MHz SuperDirective System Installation July 2005



13 MHz  
SuperDirective

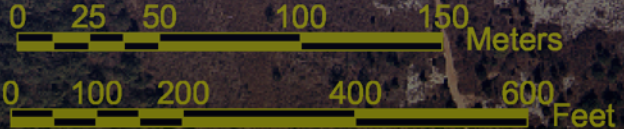
5 MHz Rx

5 MHz Tx

13 MHz Rx

25 MHz Tx/Rx

13 MHz Tx



# SuperDirective System

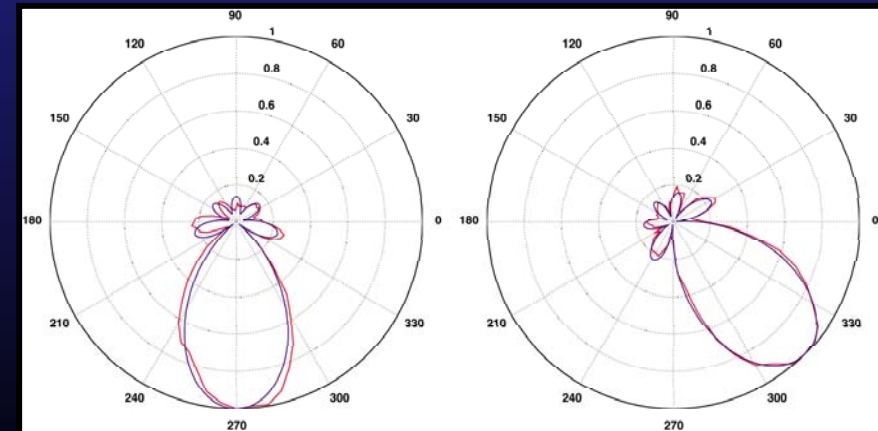
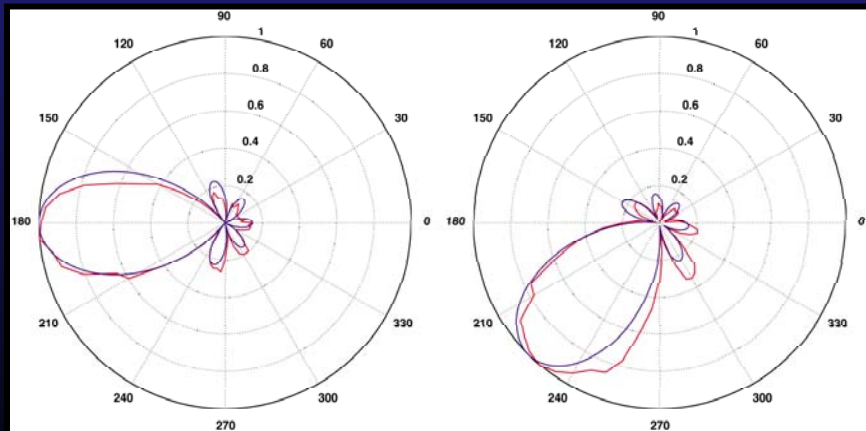
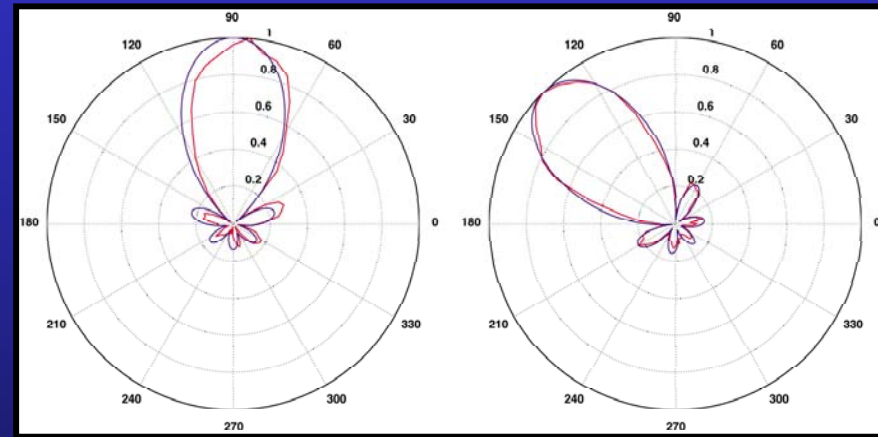
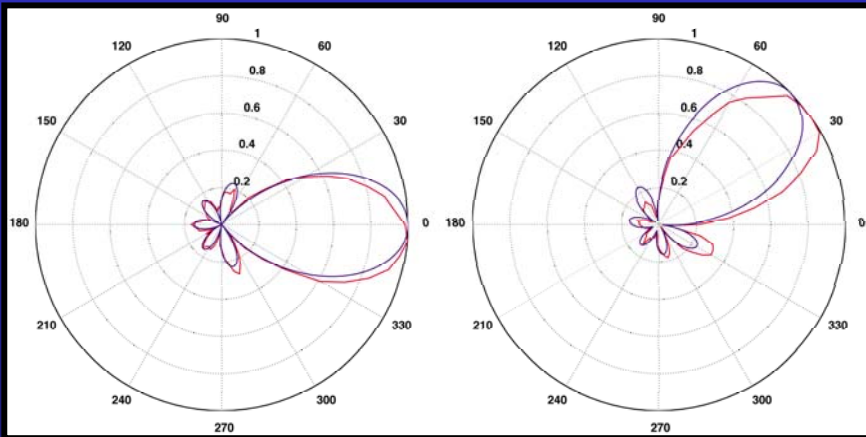
## 13-MHz Heptagonal Array Being Built and Tested at CODAR

- 23-foot (7-m) high mast
- 9-foot (3-m) arms
- 8-foot (2.7-m) dipoles
- 2 masts ~21 dB directivity over ground
- -32 dB efficiency



# SuperDirective Beam Patterns 360 degree coverage

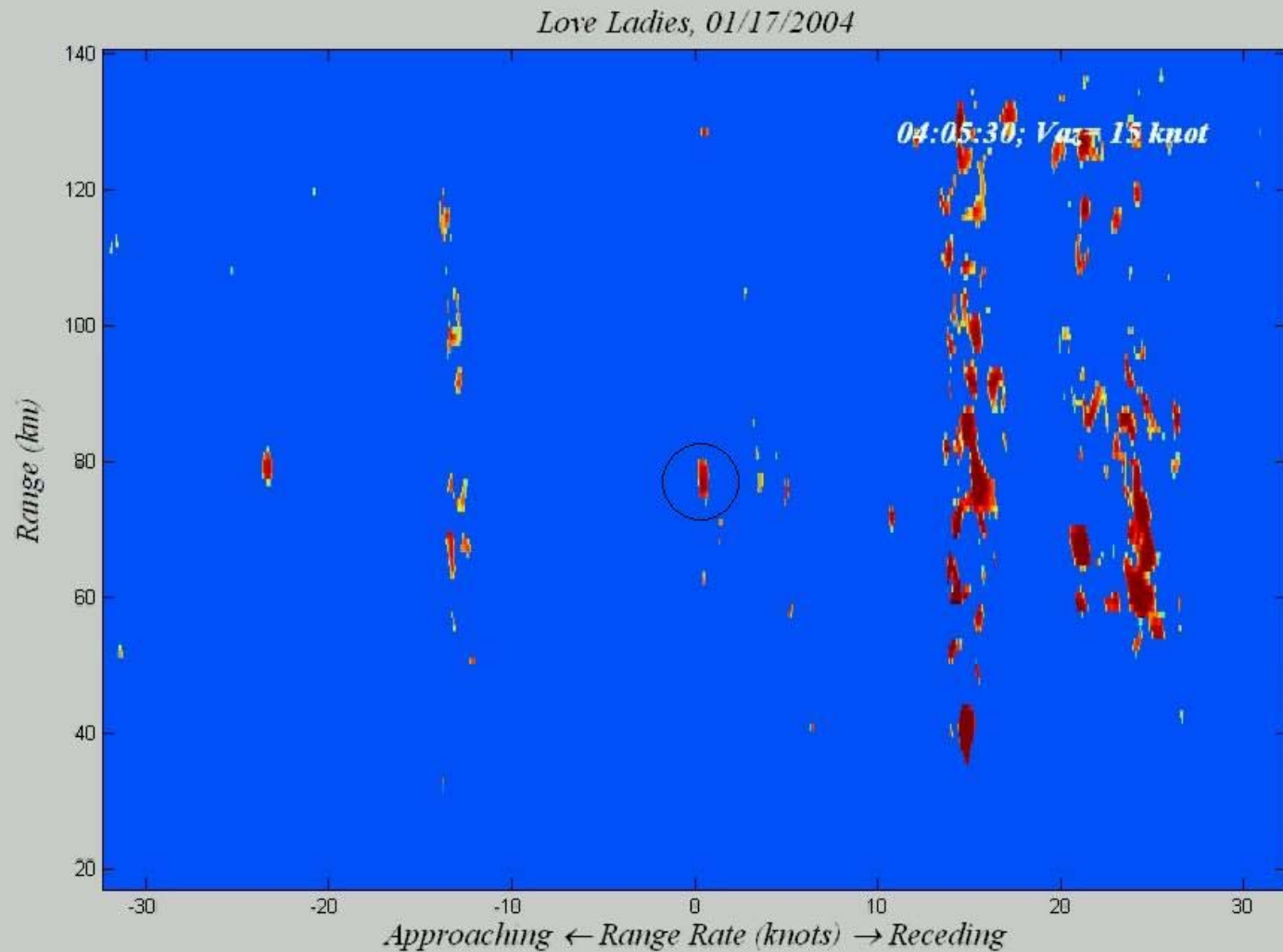
- Blue curve is theoretical pattern for 7-element array
- Red results from use of measured transponder pattern



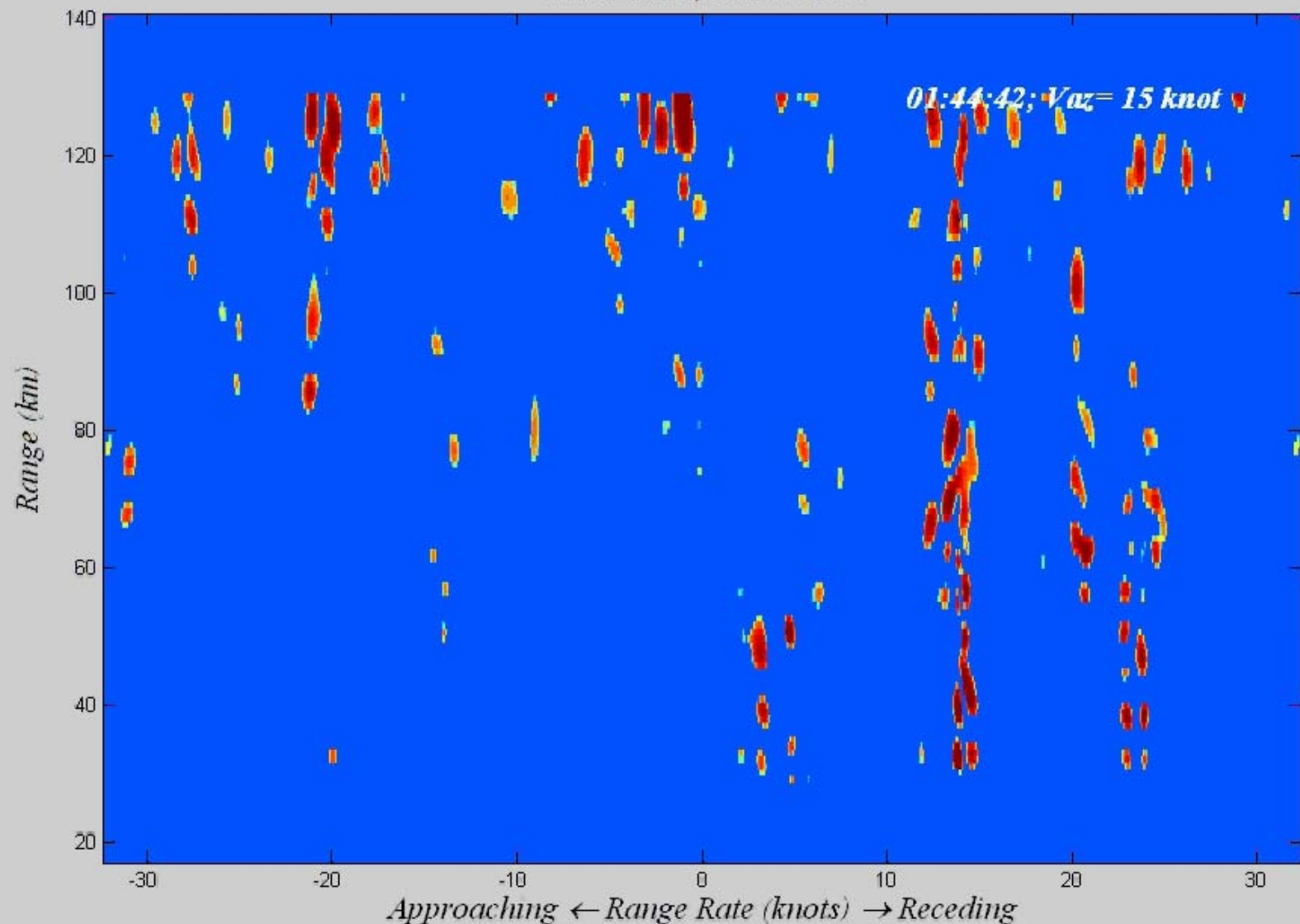
# SIGNAL INVERSION FOR TARGET EXTRACTION & REGISTRATION

- Developed by Mission Research Corporation (MRC)
- Originally developed for ROTH (Relocatable Over The Horizon Radar)
- SIFTER rejects peaks that do not move in a consistent way
- SIFTER finds “smoothest” distribution of scatterers that reproduces HFSWR or ROTH measurements
- Targets appear as localized peaks

# SIFTER Results



Love Ladies, 01/17/2004

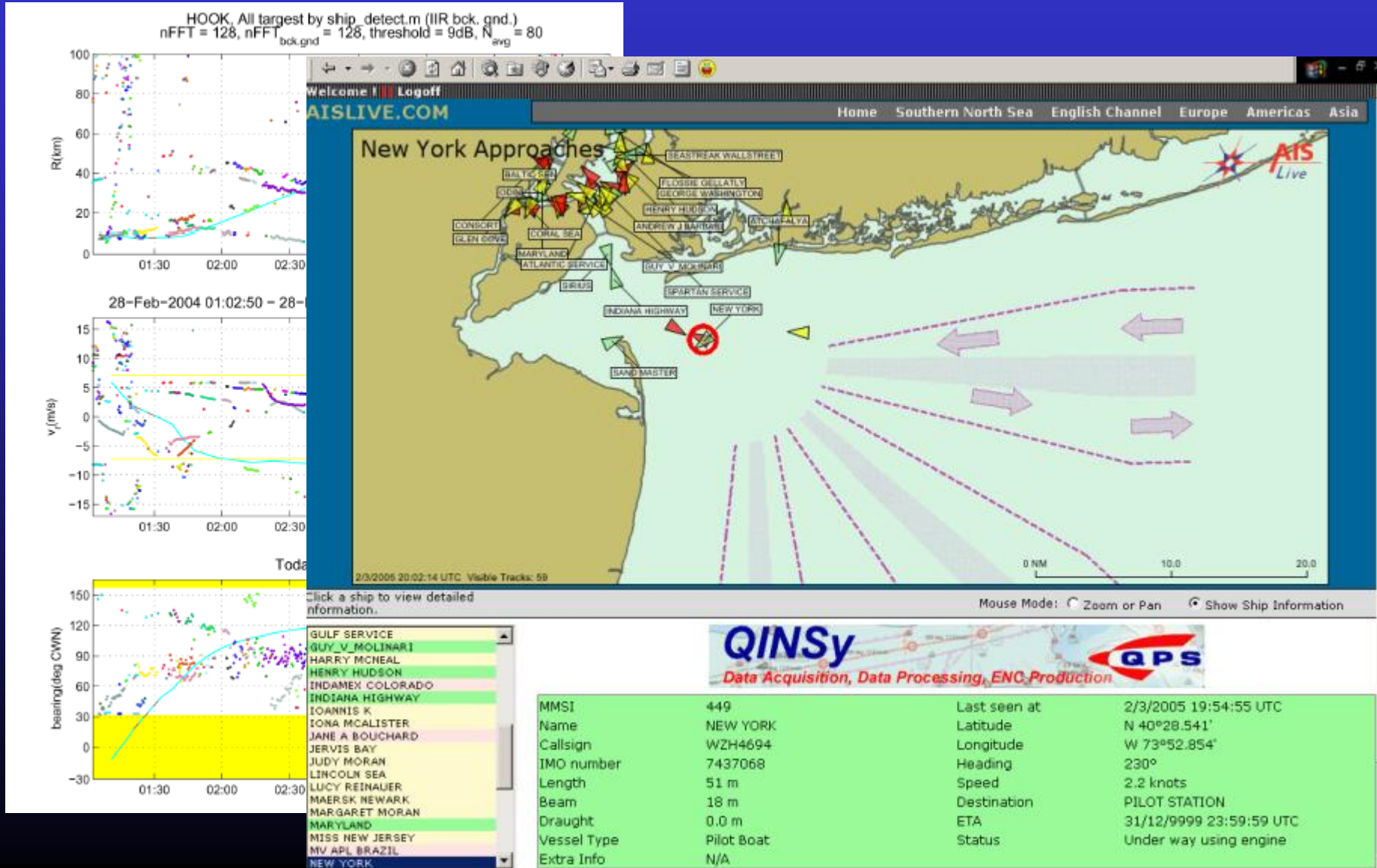


# Future Work

- Utilize AIS signal to ground truth multiple ship tracks
- New and Different Targets



# Automatic Identification System (AIS)





177' R/V Oceanographer



Patrol Boat



32' Go-Fast Boat



135' R/V Cape Hatteras



47' Motor Lifeboat

# GPS Track of RV Cape Hatteras during LATTE 2055

